On systems of multivariate power series equations



PAR JORIS VAN DER HOEVEN Lab. : LIFL, Université de Lille I, France : LIX, École polytechnique, France Email: vdhoeven@lix.polytechnique.fr Web : http://lix.polytechnique.fr:80/~vdhoeven/

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Prologue

The Newton polygon method

Problème 1

Consider the polynomial equation

$$P(f) = P_0 + P_1 f + \dots + P_d f^d = 0,$$

with power series coefficients in C[[z]]. We want an algorithm to compute the solutions.

Problème 2

Determine the asymptotique behaviour of P(f), when $z \to 0$.

Idéa

Use the Newton polygon method. Incorporate an idea of Smith [1875] (and [VdH 97]).

Asymptotic polynomial equations

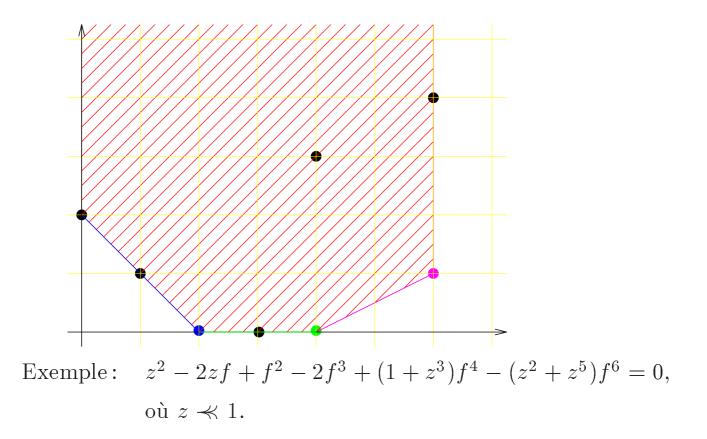
$$P(f) = P_0 + P_1 f + \dots + P_d f^d = 0 \ (f \prec \mathsf{u}).$$

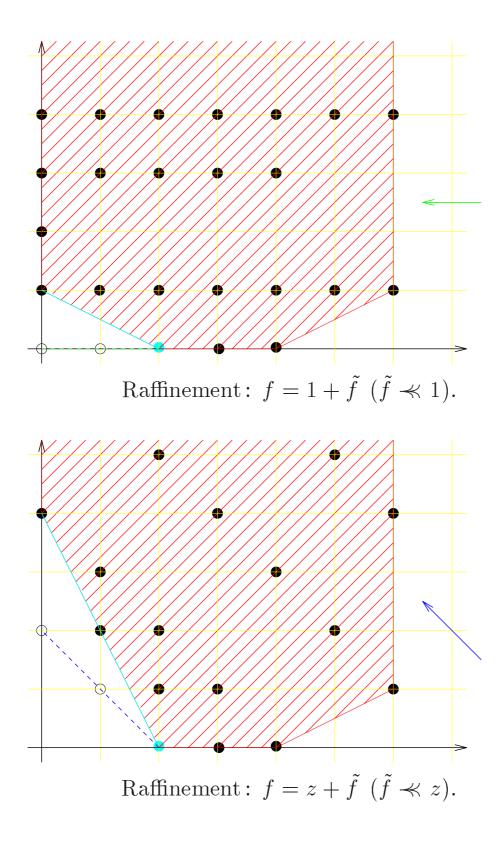
Refinements

Change of variables + constraint.

$$f = \varphi + \tilde{f} \ (\tilde{f} \prec \tilde{\mathbf{u}}), \text{ où } \tilde{\mathbf{u}} \prec \mathbf{u}.$$

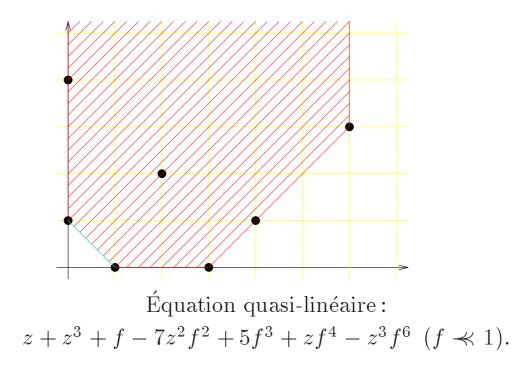
 $\label{eq:Admissible} Admissible \ refinement \longleftrightarrow one \ step \ of \ the \ Newton \ polygon \ method.$





Quasi-lineair equations

Equation of Newton degree one. Unique solution : implicit function theorem.



Smith's approch + improvement

$$f^{2} - \frac{2}{1-z}f + \frac{1}{(1-z)^{2}} = z^{10000}.$$

5000 steps necessary before root separation. Idea: solve the "derived" equation

$$2\varphi - \frac{2}{1-z} = 0,$$

and refine $f = \varphi + \tilde{f} \ (\tilde{f} \prec 1)$; one obtains $\tilde{f}^2 = z^{10000}$.

Asymptotic behaviour of P(f)

Déterminer the dominant term of P(f). Example, if $P(f) = f^2 - z^3$, the dominant term is

$$\begin{cases} f^2, \text{ if } f \not\gg z^{3/2}; \\ z^3, \text{ if } f \prec z^{3/2}; \\ (c^2 - 1)z^3, \text{ if } f = z^{3/2}(c + \tilde{f}), \text{ with } c^2 \neq 1 \text{ and } \tilde{f} \prec 1; \\ 2c\tilde{f}z^{3/2}, \text{ if } f = z^{3/2}(c + \tilde{f}), \text{ with } c^2 = 1 \text{ and } \tilde{f} \prec 1; \\ 0, \text{ if } f = z^{3/2}. \end{cases}$$

Algorithm

Newton polygon method + (improved) Smith's trick. Algorithm is non deterministic.

Multivariate series

Notations

 $C\colon$ constant field.

 \check{C} : dynamic extension of C by finite # of parameters satisfying polynomial constraints.

 $X = \{x_1, \cdots, x_p\}.$

 S_X : set of monomials $x_1^{\alpha_1} \cdots x_p^{\alpha_p}$.

 $f \in \check{C}[[S_X]]$ formal power series (generalized exponents).

 $\Sigma\colon$ set of constraints of the form

$$\begin{cases} x_1^{\alpha_1} \cdots x_p^{\alpha_p} \prec 1 & \text{ou} \\ x_1^{\alpha_1} \cdots x_p^{\alpha_p} \asymp 1. \end{cases}$$

R: region of C^p determined by Σ .

Problem

Determine the possible asymptotic behaviours of f modulo a subdivision

$$R = R_1 \amalg \cdots \amalg R_r$$

of R into a finite number of regions, determined by sets of contraints $\Sigma_1, \dots, \Sigma_p$ as above, and a series of refinements.

Idea

Introduce an elimination ordering

$$x_1 >^{elim} \cdots >^{elim} x_p.$$

Use the Newton polygon method in a lexicographical way. We will only consider refinements of the form

$$\begin{cases} x_q = \mathbf{u}(\varphi + x'_q) \ (x'_q \not\prec 1); \\ x_q = \mathbf{u}\varphi, \end{cases}$$

where $\mathbf{u} \in S_{x_{q+1},\dots,x_p}$ et $\varphi \simeq 1$ is a regular series in x_{q+1},\dots,x_p . In the last case, the variable x_q is eliminated from X.

Imposition of a constraint $\mathfrak{q} \asymp \mathfrak{q}$

Either add $\mu\mu^{-1} \approx 1$ to Σ , or apply the following algorithm constraint:

Introduce a new parameter $0 \neq \lambda \in \check{C}$. Write $\lim_{q \to 1} = x_q^{\alpha_q} \cdots x_p^{\alpha_p}$ and set $\Psi = \sqrt[\alpha_q]{x_{q+1}^{\alpha_{q-1}} \cdots x_p^{\alpha_p}}$. Separate two cases and refine

$$\left\{ \begin{array}{l} x_q = \mathrm{II}(\lambda + x_q') \ (x_q' \prec 1); \\ x_q = \lambda \mathrm{II}. \end{array} \right.$$

One step of the Newton polygon method in x_q u: a monomial in x_1, \dots, x_{q-1} . [u]f is Newton prepared if

- $[\mathbf{y}]f$ is a formal *power* series in x_q .
- There exist $\underline{\mathbf{u}}, \underline{\mathbf{u}}$ so that the dominant monomials of $[\underline{\mathbf{v}}]f$ are of the form $\underline{\mathbf{u}}(x_q/\underline{\mathbf{u}})^{\alpha}$.

Newton polynomial

$$P(\lambda) = \sum_{\alpha \in \mathbb{N}} ([\operatorname{\mathsf{um}}(x_q/\operatorname{\mathfrak{u}})^{\alpha}]f) \ \lambda^{\alpha}.$$

Newton degree : degree of P.

Algorithme Newton_step

Input: $[\mathbf{y}]f$ Newton prepared.

Action: refinement $x_q = \mathfrak{u}(\varphi + x'_q)$ $(x'_q \prec 1)$ or elimination $x_q = \mathfrak{u}\varphi$, where $\mathfrak{u}\varphi$ is a first approximation of the solution to $[\mathfrak{u}]f = 0$ in x_q .

Case when P has several roots

 $\lambda \neq 0$ new parameter in \breve{C} with $P(\lambda) = 0$. Separate two cases and refine

$$\begin{cases} x_q = \mathbf{u}(\lambda + x'_q) \ (x'_q \prec 1); \\ x_q = \lambda \mathbf{u}. \end{cases}$$

Case when P has a unique root Compute unique infinitesimal root $\mu\varphi$ of

$$\frac{\partial^{\deg P-1}([\mathbf{y}]f)}{\partial x_q^{\deg P-1}} = 0$$

in x_q , separate two cases and refine

$$\begin{cases} x_q = \mathbf{u}(\varphi + x'_q) \ (x'_q \prec 1); \\ x_q = \mathbf{u}\varphi. \end{cases}$$

Computation of the dominant monomial

While f is not regular, impose a face $F \subseteq S_X$ (finite) as being the face of dominant monomials and execute dom_sub(f, 1, F).

The algorithm dom_sub (f, \mathbf{y}, F)

Input: f, monomial \forall in x_1, \dots, x_{q-1} and F with $F_{\forall} = [\forall] F \neq \phi$. Output: either the dominant monomial \bowtie of $[\forall] f$, or the exception "recommence".

Case 1: \exists unique α with $F_{\forall x_q^{\alpha}} \neq \phi$. Return dom_sub $(f, \forall x_q^{\alpha}, F) x_q^{\alpha}$.

Case 2: f is not a formal *power* series in x_q . Choose $\mathfrak{u} \in F$ and execute $\operatorname{constraint}(\mathfrak{u} \asymp \mathfrak{u})$ for each other $\mathfrak{u} \in F_{\mathfrak{u}}$. Otherwise, separate cases 3 and 4:

Case 3: non singular case.

Choose μ arbitrary in F.

Execute constraint $(\mathfrak{u} \asymp \mathfrak{m})$ for each other $\mathfrak{m} \in F$.

Let M be the unique element of $F_{\mathbf{u}}$ after rewriting. Return M.

Case 4: singular case.

(Idea: one step of Newton polygon method)

For each α with $F_{\mathbf{u}x_q^{\alpha}} \neq \phi$, execute dom_sub $(f, \mathbf{u}x_q^{\alpha}, F)$.

Let n be the # of times dom_sub does not return "recommence". If n = 0, return "recommence".

If n = 1, kill the process.

Otherwise, choose $\mathbf{u} = \mathbf{u} x_q^{\alpha} \mathbf{m}$ and $\mathbf{u}' = \mathbf{u} x_q^{\alpha'} \mathbf{m}' \in F_{\mathbf{u}}$ with $\alpha' \neq \alpha$. Execute constraint $(\mathbf{m}^{\alpha''-\alpha'} \mathbf{m}'^{\alpha-\alpha''} \mathbf{m}''^{\alpha'-\alpha} \asymp 1)$ for each $\mathbf{u}'' = \mathbf{u} x_q^{\alpha''} \mathbf{m}'' \in F_{\mathbf{u}}$.

Execute Newton_step($[\mathbf{y}]f$) and return "recommence".