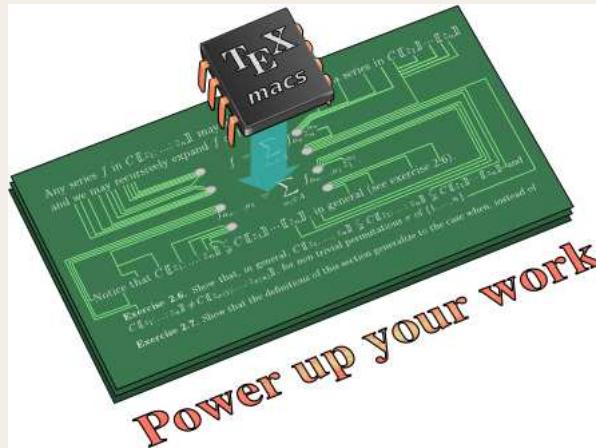


Effective real numbers

by Joris van der Hoeven



Presentation with **GNU TEXmacs** (www.texmacs.org)



Effective real numbers in MMXLIB



```
Mmx >> x: Real == sin sin real 2;
```

```
Mmx >> x
```

$7.891 \cdot 10^{-1}$

Real

```
Mmx >> approximate(x, 1.0e-35);
```

$7.8907234357288836143140304248688412 \cdot 10^{-1}$

Interval

```
Mmx >> M: Matrix Real == ( x   x + 2  
                           2 - x^2   cos x );
```

```
Mmx >> M;
```

$$\begin{bmatrix} 7.891 \cdot 10^{-1} & 2.789 \\ 1.377 & 7.045 \cdot 10^{-1} \end{bmatrix}$$

Matrix(Real)

```
Mmx >> M^20;
```

$$\begin{bmatrix} 2.284 \cdot 10^8 & 3.181 \cdot 10^8 \\ 1.571 \cdot 10^8 & 2.188 \cdot 10^8 \end{bmatrix}$$

Matrix(Real)

```
Mmx >> exp(x + exp(-real 100)) - exp(x);
```

$8.189 \cdot 10^{-44}$

Real

```
Mmx >> exp(x + exp(-real 1000)) - exp(x);
```

0

Real

Mmx >>



Effective analytic functions in MMXLIB



```
Mmx >> z: Analytic == analytic(0, 1);
```

```
Mmx >> exp(z);
```

$$1.000 + 1.000 z + 5.000 \cdot 10^{-1} z^2 + 1.667 \cdot 10^{-1} z^3 + 4.167 \cdot 10^{-2} z^4 + 8.333 \cdot 10^{-3} z^5 + 1.389 \cdot 10^{-3} z^6 + 1.984 \cdot 10^{-4} z^7 + 2.480 \cdot 10^{-5} z^8 + 2.756 \cdot 10^{-6} z^9 + O(z^{10})$$

Analytic

```
Mmx >> exp(z)[int 20];
```

$$4.110 \cdot 10^{-19}$$

Complex

```
Mmx >> ℓ: Analytic == log(1 - z);
```

```
Mmx >> radius(ℓ);
```

$$9.99937726184725761359 \cdot 10^{-1}$$

Floating

```
Mmx >> evaluate(ℓ, complex(1/2));
```

$$-6.931 \cdot 10^{-1}$$

Complex

```
Mmx >> continuant(ℓ, complex(1/2));
```

$$-6.931 \cdot 10^{-1} - 2.000 z - 2.000 z^2 - 2.667 z^3 - 4.000 z^4 - 6.400 z^5 - 1.067 \cdot 10^1 z^6 - 1.829 \cdot 10^1 z^7 - 3.200 \cdot 10^1 z^8 - 5.689 \cdot 10^1 z^9 + O(z^{10})$$

Analytic

```
Mmx >> continuant(ℓ, turn(complex(1)));
```

$$6.283 i - 1.000 z - 5.000 \cdot 10^{-1} z^2 - 3.333 \cdot 10^{-1} z^3 - 2.500 \cdot 10^{-1} z^4 - 2.000 \cdot 10^{-1} z^5 - 1.667 \cdot 10^{-1} z^6 - 1.429 \cdot 10^{-1} z^7 - 1.250 \cdot 10^{-1} z^8 - 1.111 \cdot 10^{-1} z^9 + O(z^{10})$$

Analytic

Mmx >>



Solving differential equations



$$f'' = (z^2 + 1) f' + e^z f; \quad f(0) = 1, f'(0) = 1 + 2i.$$

```
Mmx >> f: Analytic=solve_lde((z^2+1, exp(z)), (complex(1), complex(1, 2)));
```

```
Mmx >> f;
```

$$1.000 + (1.000 + 2.000 i) z + (1.000 + 1.000 i) z^2 + (6.667 \cdot 10^{-1} + 1.000 i) z^3 + (5.417 \cdot 10^{-1} + 5.833 \cdot 10^{-1} i) z^4 + (3.500 \cdot 10^{-1} + 4.833 \cdot 10^{-1} i) z^5 + (2.278 \cdot 10^{-1} + 2.750 \cdot 10^{-1} i) z^6 + (1.343 \cdot 10^{-1} + 1.742 \cdot 10^{-1} i) z^7 + (7.882 \cdot 10^{-2} + 9.767 \cdot 10^{-2} i) z^8 + (4.361 \cdot 10^{-2} + 5.572 \cdot 10^{-2} i) z^9 + O(z^{10}) \quad \text{Analytic}$$

```
Mmx >> u: Complex=evaluate(f, complex(1/10));
```

```
Mmx >> u;
```

$$1.111 + 2.111 \cdot 10^{-1} i$$

Complex

```
Mmx >> approximate(u, 1.0e-81);
```

$$1.11072457537794457102292725574830566357052541308848196626687047567517902828392834 + 2.1106346012282867466007605052618438398248510727864880851400427655460836641117663 \cdot 10^{-1} i \\ \text{Complexify(Interval)}$$

```
Mmx >>
```



Definition of effective real numbers



- $\tilde{x} \in \mathbb{D} = \mathbb{Z} 2^{\mathbb{Z}}$ is an ε -approximation of $x \in \mathbb{R}$ if $|\tilde{x} - x| < \varepsilon$.
- *Approximation algorithm* for x : computes $\varepsilon \mapsto \varepsilon$ -approximation of x .
- *Effective real number*: $x \in \mathbb{R}$ which admits an approximation algorithm.
- *Complexity* of x : time needed to compute a 2^{-l} -approximation.
- Implementation of real as pointer to

```
class real_rep {  
public:  
    virtual dyadic approximate (const dyadic& err) = 0;  
    ...  
};
```

- No zero-test for effective real numbers.
- References: Bishop and Bridges, Blanck, Müller, vdH, etc.



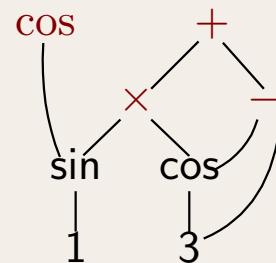
Modeling computations with effective real numbers



- Example: addition

```
class add_real_rep: public real_rep {  
    real x, y;  
    add_real_rep (const real& x2, const real& y2):  
        x (x2), y (y2) {}  
    dyadic approximate (const dyadic& eps) {  
        return x->approximate (eps/2) + y->approximate (eps/2); }  
};
```

- Model sets of effective real numbers by acyclic graphs:



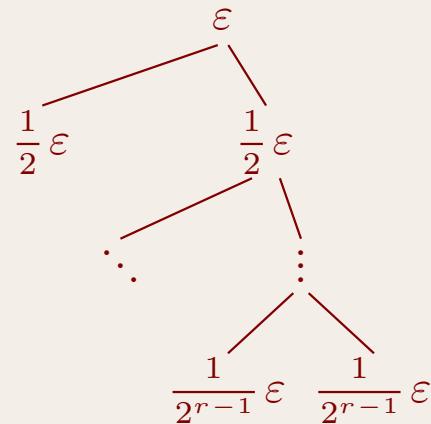
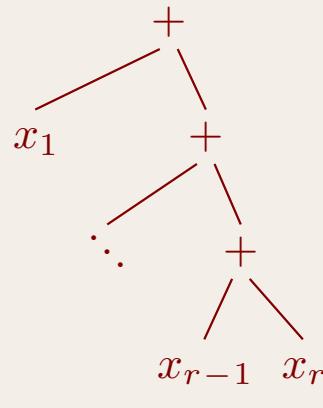
- Computations stored in memory → don't use classical numerical algorithms.



A *priori* error estimates



- Distribute tolerance ε *a priori* over nodes of n -ary operations ($n > 1$).
- Can be bad in case of badly nested expressions:



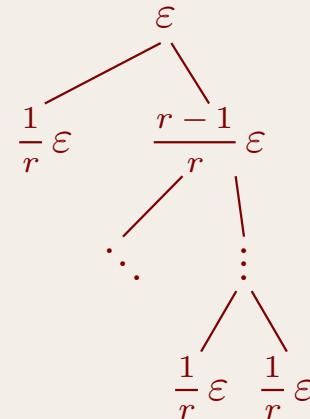
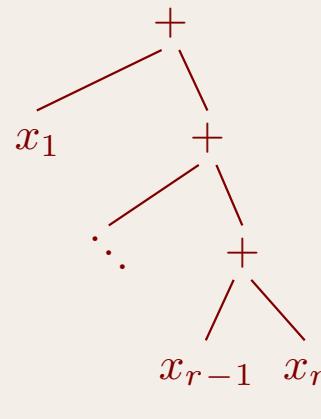
- Possible loss of $\log w$ bits of precision; still unacceptable.



A *priori* error estimates



- Distribute tolerance ε *a priori* over nodes of n -ary operations ($n > 1$).
- Balanced error estimates: redistribute as a function of *weight*:



- Possible loss of $\log w$ bits of precision; still unacceptable.



A posteriori error estimates



- Perform whole computation using interval arithmetic.

While result not precise enough:

 Double precision and redo entire computation.

- First improvement:

 For each instance of `real_rep`, keep best current approximation in memory.

- Second improvement:

 Don't double precision, but estimated computation time.



Representation of intervals



- $W = 16, 32, 64, 128, \dots$ bit precision of the processor.
- \mathbb{D}_l set of generalized IEEE 754 numbers of precision l and fixed exponent range.
- Standard representation at precision l
 - $x = [\underline{x}, \bar{x}]$, with $\underline{x} \leq \bar{x} \in \mathbb{D}_l \setminus \{\text{NaN}\}$ or $x = \text{NaIn}$.
 - Easy to implement on top of MPFR.
 - Inherits standardization from IEEE 754.
 - Requires two l -bit computations for each operation.



Representation of intervals



- $W = 16, 32, 64, 128, \dots$ bit precision of the processor.
- \mathbb{D}_l set of generalized IEEE 754 numbers of precision l and fixed exponent range.
- Ball representation at precision l

$$x = \mathcal{B}(c_x, r_x) \text{ with } \begin{cases} c_x \in \mathbb{D}_l \notin \{\text{NaN}, \pm 0, \pm \infty\} \\ r_x \in \mathbb{D}_l^{\geqslant}, l > W \Rightarrow r_x \leqslant |c_x| 2^{W-l} \end{cases} \text{ or } x = \text{NaIn}$$

- Efficient and easy to implement for high precisions.
- Less expressive power: cannot represent $[0, \infty]$.
- Difficult to preserve positivity: $\mathcal{B}(a, a) + \mathcal{B}(b, b)$.



Representation of intervals



- $W = 16, 32, 64, 128, \dots$ bit precision of the processor.
- \mathbb{D}_l set of generalized IEEE 754 numbers of precision l and fixed exponent range.
- Hybrid representation at precision l

Use standard representation for $l = W$.

Use ball representation for $l > W$.



Semantics and standardization



- Precision loss and normalization

Example: $2.0060000000123 - 2.0060000000000 \rightarrow 1.23 \times 10^{-10}$.

- Set of intervals at precision l not stable under $+$, $-$, \times , etc.
- Set \mathbb{I}_l of intervals at precision $\leq l$ is stable under $+$, $-$, \times , etc.

- Precision gains

Example 1: $\log_{10} 1.0 \times 10^{1000} \rightarrow 1.0000 \times 10^3$.

Example 2: $\arctan 1.0 \times 10^{10} \rightarrow 1.5707963267$.

- We compute with precision $\min(l, \text{precision arguments})$.

- Semantics

- Perform operation as if we use l bit precision in standard representation.
- Normalize result to hybrid representation.
- Return NaIn as soon as error occurs for one possible value.
- Loosen: allow for 2^{-W} relative errors.



Template types over interval



- Complex numbers

```
Mmx >> forall(T) power(x: T, n: Integer): T ==
          (if n = 1 then x else x power(x, n - 1));
```

```
Mmx >> alpha: Interval == approximate(real2, 1.0e-24); alpha;
```

2.000000000000000000000000000000

Interval

Mmx $\gg \beta$: Complexify Interval \equiv approximate(complex(1, 1), 1.0e-24); β ;

$1.000000000000000000000000000000 + 1.000000000000000000000000000000i$

Complexify(Interval)

Mmx \gg for i : Integer in 1...10 loop mmout \ll power(β , 8*i*) \ll "n";

$$4.096000000000000000000000 \cdot 10^3 \pm 0.010^{-19} i$$

$$6.553600000000000 \cdot 10^4 + 0.0 \cdot 10^{-16} i$$

$$1.0485760000000000 \cdot 10^6 + 0.0 \cdot 10^{-14} i$$

$$1.677721600000000 \cdot 10^7 \pm 0.010^{-11} \mathrm{i}$$

$$2.68435456000000 \cdot 10^8 \pm 0.010^{-9} i$$

$$4.2949672960000 \cdot 10^9 \pm 0.010^{-7} i$$

$$6.87194767360010^{10} \pm 0.010^{-4} \text{ j}$$

$$1.09951162778 \times 10^{12} + 0.010^{-2} i$$

$\mathbf{y}_i \gg \mathbf{f}_{\text{out}}(\mathbf{I}, t_i) \approx -1 \cdot 10^1$, $t_i \ll 28^i \ll \infty$)

$$M_{mx} \gg$$

Systematically use ball representation.

- Matrices

Compute matrix products $M_1 \cdots M_n$ by dichotomy.

For instance: $M_1 \cdots M_8 = (((M_1 M_2) (M_3 M_4)) ((M_5 M_6) (M_7 M_8)))$

- Truncated power series

First renormalize $f(z) \mapsto f(\rho z)$.



Implementing effective real numbers I



Representation and main methods

```
class real_rep {  
protected:  
    double    cost;  
    interval best;  
  
public:  
    virtual interval compute () = 0;  
    virtual int precision_for (double cost) = 0;  
  
    real_rep (): cost (1.0), best (compute ()) {}  
    interval improve (double new_cost);  
    interval approximate (const dyadic& err);  
};
```



Implementing effective real numbers II



Improving the approximation

```
interval real_rep::improve (double new_cost) {  
    if (new_cost <= cost) return best;  
    cost= max (new_cost, 2.0 * cost);  
    set_precision (precision_for (cost));  
    best= compute ();  
    restore_precision ();  
    return best;  
}  
  
interval real_rep::approximate (const dyadic& err) {  
    while (radius (best) >= err)  
        (void) improve (2 * cost);  
    return best;  
}
```



Global approximation problem

Input: an acyclic graph G with for each node $\alpha \in G$:

- A real function f_α from the library.

Induces by induction a real number $x_\alpha = f_\alpha(x_{\alpha[1]}, \dots, x_{\alpha[|\alpha|]})$.

- A tolerance $\varepsilon_\alpha \in \mathbb{D}^>$.

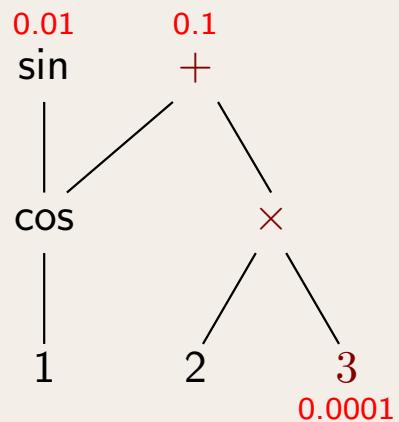
Output: for each node an interval $\mathbf{x}_\alpha \ni x_\alpha$ with

- $r_{\mathbf{x}_\alpha} < \varepsilon_\alpha$.
- $\mathbf{x}_\alpha \supseteq f_\alpha(\mathbf{x}_{\alpha[1]}, \dots, \mathbf{x}_{\alpha[|\alpha|]})$.

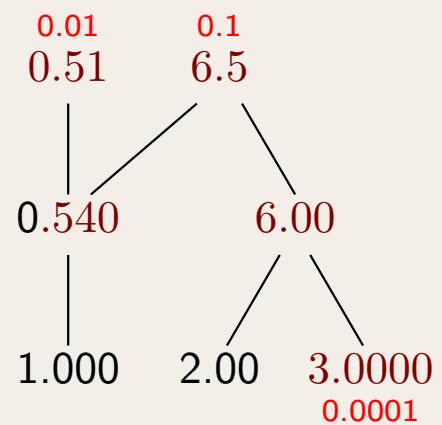
Drawbacks

- Does not model incremental computations.
- No dependency of computations on intermediate results.

Example



Example





Total versus final computation cost



For each node $\alpha \in G$, let

- $T_{\alpha,1}, \dots, T_{\alpha,p_\alpha}$: requested costs of the successive evaluations of x_α .
- $t_{\alpha,1}, \dots, t_{\alpha,p_\alpha}$: actual costs of the successive evaluations of x_α .
- $t_\alpha = t_{\alpha,1} + \dots + t_{\alpha,p_\alpha}$ and $t_\alpha^{\text{fin}} = t_{\alpha,p_\alpha}$

By construction $T_{\alpha,1} = 1, T_{\alpha,2} = 2, T_{\alpha,3} = 4, \dots$

However, we do **not** necessarily have $t_{\alpha,i} = T_{\alpha,i}$, unless α is a leaf.

Indeed: $x = -y$, where y admits a slow approximation algorithm.



Total versus final computation cost



For each node $\alpha \in G$, let

- $T_{\alpha,1}, \dots, T_{\alpha,p_\alpha}$: requested costs of the successive evaluations of x_α .
- $t_{\alpha,1}, \dots, t_{\alpha,p_\alpha}$: actual costs of the successive evaluations of x_α .
- $t_\alpha = t_{\alpha,1} + \dots + t_{\alpha,p_\alpha}$ and $t_\alpha^{\text{fin}} = t_{\alpha,p_\alpha}$

Nevertheless: for each α , we have $t_{\alpha,1} \leq \dots \leq t_{\alpha,p_\alpha}$.

Let λ be a node for which $p = p_\lambda$ is maximal (necessarily a leaf).

Setting $t = \sum_\alpha t_\alpha$ and $t^{\text{fin}} = \sum_\alpha t_\alpha^{\text{fin}}$, we then have

$$t = \sum_{\alpha,i} t_{\alpha,i} \leq \sum_\alpha p_\alpha t_\alpha^{\text{fin}} \leq p t^{\text{fin}}.$$

It follows that

$$t^{\text{fin}} \leq t \leq (\log_2 t^{\text{fin}}) t^{\text{fin}}.$$



Final versus optimal computation cost



Now consider an optimal solution and let

- t_α^{opt} time spent to compute \mathbf{x}_α .
- $t^{\text{opt}} = \sum_\alpha t_\alpha^{\text{opt}}$.

Denoting by s the size of G , it can be shown that

$$t^{\text{opt}} \leq t^{\text{fin}} \leq 2s t^{\text{opt}}.$$

This bound is nevertheless “optimal”:

$$\mathbf{y} = x_1 \cdots x_n,$$

with $x_1 = \cdots = x_n = 0$ and exactly one of the \mathbf{x}_i has a slow approximation algorithm.