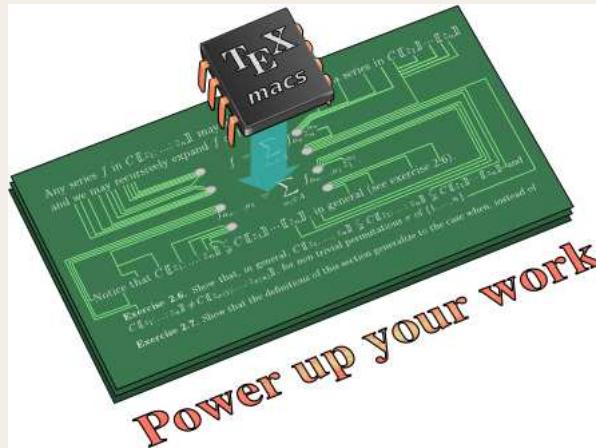


Effective real numbers in MMXLIB

by Joris van der Hoeven



Presentation with **GNU TEXmacs** (www.texmacs.org)



Effective real numbers in MMXLIB



<http://www.mathemagix.org/mmxweb/web/welcome-mml.en.html>

Mmx $\gg x$: Real $= \sin \sin \text{real} 2;$

Mmx $\gg x$

$7.891 \cdot 10^{-1}$

Real

Mmx $\gg \text{approximate}(x, 1.0e-35);$

$7.8907234357288836143140304248688412 \cdot 10^{-1}$

Interval

Mmx $\gg M$: Matrix Real $= \begin{pmatrix} x & x+2 \\ 2-x^2 & \cos x \end{pmatrix};$

Mmx $\gg M;$

$\begin{bmatrix} 7.891 \cdot 10^{-1} & 2.789 \\ 1.377 & 7.045 \cdot 10^{-1} \end{bmatrix}$

Matrix(Real)

Mmx $\gg M^{20};$

$\begin{bmatrix} 2.284 \cdot 10^8 & 3.181 \cdot 10^8 \\ 1.571 \cdot 10^8 & 2.188 \cdot 10^8 \end{bmatrix}$

Matrix(Real)

Mmx $\gg \exp(x + \exp(-\text{real} 100)) - \exp(x);$

$8.189 \cdot 10^{-44}$

Real

Mmx $\gg \exp(x + \exp(-\text{real} 1000)) - \exp(x);$

0

Real

Mmx >>



Effective analytic functions in MMXLIB



```
Mmx >> z: Analytic == analytic(0, 1);
```

```
Mmx >> exp(z);
```

$$1.000 + 1.000 z + 5.000 \cdot 10^{-1} z^2 + 1.667 \cdot 10^{-1} z^3 + 4.167 \cdot 10^{-2} z^4 + 8.333 \cdot 10^{-3} z^5 + 1.389 \cdot 10^{-3} z^6 + 1.984 \cdot 10^{-4} z^7 + 2.480 \cdot 10^{-5} z^8 + 2.756 \cdot 10^{-6} z^9 + O(z^{10})$$

Analytic

```
Mmx >> exp(z)[int 20];
```

$$4.110 \cdot 10^{-19}$$

Complex

```
Mmx >> ℓ: Analytic == log(1 - z);
```

```
Mmx >> radius(ℓ);
```

$$9.99937726184725761359 \cdot 10^{-1}$$

Floating

```
Mmx >> evaluate(ℓ, complex(1/2));
```

$$-6.931 \cdot 10^{-1}$$

Complex

```
Mmx >> continuant(ℓ, complex(1/2));
```

$$-6.931 \cdot 10^{-1} - 2.000 z - 2.000 z^2 - 2.667 z^3 - 4.000 z^4 - 6.400 z^5 - 1.067 \cdot 10^1 z^6 - 1.829 \cdot 10^1 z^7 - 3.200 \cdot 10^1 z^8 - 5.689 \cdot 10^1 z^9 + O(z^{10})$$

Analytic

```
Mmx >> continuant(ℓ, turn(complex(1)));
```

$$6.283 i - 1.000 z - 5.000 \cdot 10^{-1} z^2 - 3.333 \cdot 10^{-1} z^3 - 2.500 \cdot 10^{-1} z^4 - 2.000 \cdot 10^{-1} z^5 - 1.667 \cdot 10^{-1} z^6 - 1.429 \cdot 10^{-1} z^7 - 1.250 \cdot 10^{-1} z^8 - 1.111 \cdot 10^{-1} z^9 + O(z^{10})$$

Analytic

Mmx >>



Solving differential equations



$$f'' = (z^2 + 1) f' + e^z f; \quad f(0) = 1, f'(0) = 1 + 2i.$$

```
Mmx >> f: Analytic=solve_lde((z^2+1, exp(z)), (complex(1), complex(1, 2)));
```

```
Mmx >> f;
```

$$1.000 + (1.000 + 2.000 i) z + (1.000 + 1.000 i) z^2 + (6.667 \cdot 10^{-1} + 1.000 i) z^3 + (5.417 \cdot 10^{-1} + 5.833 \cdot 10^{-1} i) z^4 + (3.500 \cdot 10^{-1} + 4.833 \cdot 10^{-1} i) z^5 + (2.278 \cdot 10^{-1} + 2.750 \cdot 10^{-1} i) z^6 + (1.343 \cdot 10^{-1} + 1.742 \cdot 10^{-1} i) z^7 + (7.882 \cdot 10^{-2} + 9.767 \cdot 10^{-2} i) z^8 + (4.361 \cdot 10^{-2} + 5.572 \cdot 10^{-2} i) z^9 + O(z^{10}) \quad \text{Analytic}$$

```
Mmx >> u: Complex=evaluate(f, complex(1/10));
```

```
Mmx >> u;
```

$$1.111 + 2.111 \cdot 10^{-1} i \quad \text{Complex}$$

```
Mmx >> approximate(u, 1.0e-81);
```

$$1.11072457537794457102292725574830566357052541308848196626687047567517902828392834 + \\ 2.1106346012282867466007605052618438398248510727864880851400427655460836641117663 \cdot 10^{-1} i \\ \text{Complexify(Interval)}$$

```
Mmx >>
```



Definition of effective real numbers



- $\tilde{x} \in \mathbb{D} = \mathbb{Z} 2^{\mathbb{Z}}$ is an ε -approximation of $x \in \mathbb{R}$ if $|\tilde{x} - x| < \varepsilon$.
- *Approximation algorithm* for x : computes $\varepsilon \mapsto \varepsilon$ -approximation of x .
- *Effective real number*: $x \in \mathbb{R}$ which admits an approximation algorithm.
- *Complexity* of x : time needed to compute a 2^{-l} -approximation.
- No zero-test for effective real numbers.
- References: Bishop and Bridges, Blanck, Müller, vdH, etc.



Implementation by layers



Fast arithmetic.

Fast computations on mantissas (Karatsuba, FFT, Brent, Chudnovsky², VdH, etc.).

Implementations: GMP, CLN, ...

Low-level validated arithmetic.

Correct rounding or well-specified bounds on the error.

Implementations: MPFR, ...

High-level validated arithmetic.

Template types for intervals, balls, Lipschitz balls, etc.

Implementations: MPFI, IRRAM, MMXLIB, ...

High-level interface.

Given a required precision for the result, automatically find precisions for all intermediate computations.

Implementations: IRRAM, MMXLIB, ...



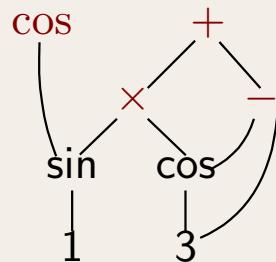
Modeling computations with effective real numbers



- Example: addition

```
class add_real_rep: public real_rep {  
    real x, y;  
    add_real_rep (const real& x2, const real& y2):  
        x (x2), y (y2) {}  
    dyadic approximate (const dyadic& eps) {  
        return x->approximate (eps/2) + y->approximate (eps/2); }  
};
```

- Model sets of effective real numbers by acyclic graphs:



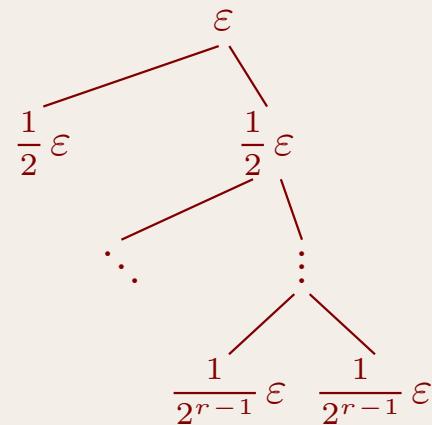
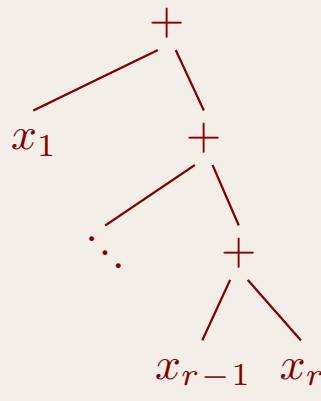
- Computations stored in memory → don't use classical numerical algorithms.



A *priori* error estimates



- Distribute tolerance ε *a priori* over nodes of n -ary operations ($n > 1$).
- Can be bad in case of badly nested expressions:



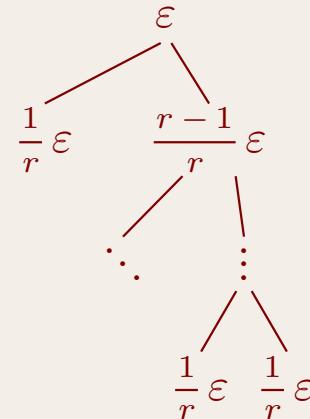
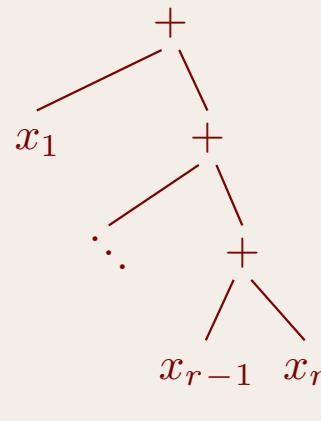
- Possible loss of $\log w$ bits of precision; still unacceptable.



A *priori* error estimates



- Distribute tolerance ε *a priori* over nodes of n -ary operations ($n > 1$).
- Balanced error estimates: redistribute as a function of *weight*:



- Possible loss of $\log w$ bits of precision; still unacceptable.



A posteriori error estimates



- Perform whole computation using interval arithmetic.

While result not precise enough:

 Double precision and redo entire computation.

- First improvement:

 For each instance of `real_rep`, keep best current approximation in memory.

- Second improvement:

 Don't double precision, but estimated computation time.



Global approximation problem

Input: an acyclic graph G with for each node $\alpha \in G$:

- A real function f_α from the library.

Induces by induction a real number $x_\alpha = f_\alpha(x_{\alpha[1]}, \dots, x_{\alpha[|\alpha|]})$.

- A tolerance $\varepsilon_\alpha \in \mathbb{D}^>$.

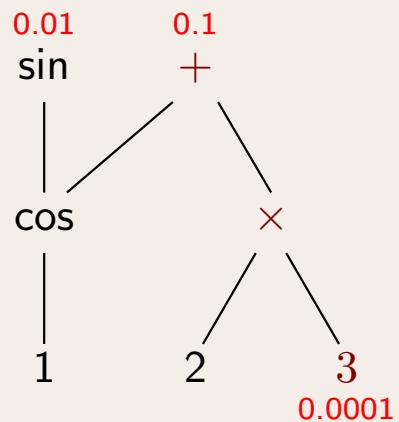
Output: for each node an interval $\mathbf{x}_\alpha \ni x_\alpha$ with

- $r_{\mathbf{x}_\alpha} < \varepsilon_\alpha$.
- $\mathbf{x}_\alpha \supseteq f_\alpha(\mathbf{x}_{\alpha[1]}, \dots, \mathbf{x}_{\alpha[|\alpha|]})$.

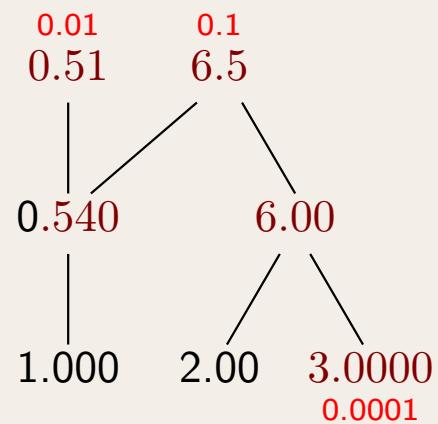
Drawbacks

- Does not model incremental computations.
- No dependency of computations on intermediate results.

Example



Example





Results



Doubling computation time approach

- Final complexity vs. total complexity $t^{\text{fin}} \leq t \leq (\log_2 t^{\text{fin}}) t^{\text{fin}}$.
- Final complexity vs. optimal complexity $t^{\text{opt}} \leq t^{\text{fin}} \leq 2 s t^{\text{opt}}$.

Faster approaches in “the rigid case”

- Rigid dag: for each $x_\alpha = f_\alpha(x_{\alpha[1]}, \dots, x_{\alpha[|\alpha|]})$, the $\partial x_\alpha / \partial x_{\alpha[i]}$ are known with a fixed relative precision (say $1/2$).
- A sufficient precision can be determined quite sharply beforehand (IRRAM).
- Using backward error bounds and balancing, the precisions can be adapted locally in a quasi-optimal way.