Probably faster multiplication of sparse polynomials^{*†}

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In this paper, we present a probabilistic algorithm to multiply two sparse polynomials almost as efficiently as two dense univariate polynomials with a result of approximately the same size. The algorithm depends on unproven heuristics that will be made precise.

1. INTRODUCTION

Let $P, Q \in \mathbb{Z}[x_1, ..., x_n]$ be polynomials that are represented in the usual way as linear combinations of power products. The problem of *sparse polynomial multiplication* is to compute the product R = PQ in a way that is as efficient as possible in terms of the total bitsize of P, Q, and R (and where we use a similar *sparse representation* for R as for P and Q).

For pedagogical reasons, we mainly restrict our attention to polynomials with integer coefficients. Together with polynomials with rational coefficients, this is indeed the most important case for practical implementations inside computer algebra systems. Nevertheless, it is not hard to adapt our techniques to coefficients in more general rings (some indications to that effect are given in section 5.2). Still for pedagogical reasons, we will carry out our complexity analysis in the RAM model [11]. We expect our algorithms to adapt to the Turing model [13], but more work will be needed to prove this and some of the constant factors might deteriorate.

For polynomials of modest size, naive algorithms are often most efficient. We refer to [3, 6, 10, 19, 28, 32, 33, 37] for implementation techniques that are efficient in practice. Various types of faster algorithms have been proposed for polynomials with special supports [16, 18, 23, 35].

Asymptotically fast methods for polynomials of large sizes usually rely on sparse interpolation. The seminal paper by Ben Or and Tiwari [4] triggered the development of many fast algorithms for the sparse interpolation of polynomial blackbox functions [1, 5, 9, 20, 24, 25, 26, 27, 29, 34]. In this framework, the unknown polynomial *R* is given through a blackbox functions that can be evaluated at points in suitable extensions of the coefficient ring. We refer to [36] for a nice survey on sparse interpolation and other algorithms to compute with sparse polynomials. The present paper grew out of our recent preprint [21] with Grégoire Lecerf on this topic; the idea to "exploit colliding terms" in section 6.6 forms the starting point of our work.

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The most efficient algorithms for sparse interpolation are mostly probabilistic. Here we note that it is usually easy to check that the result is correct with high probability: just evaluate both the blackbox function and its supposed interpolation at a random point and verify that both evaluations coincide. In this paper, all algorithms will be probabilistic, which is suitable for the practical purposes that we are interested in. The running times of our algorithms also rely on suitable heuristics that we will make precise.

Although the multiplication problem for sparse polynomials does not directly fit into the usual blackbox model, it does benefit from the techniques that have been developed for sparse interpolation. Practical algorithms along these lines have appeared in [8, 12, 19, 31]. Most algorithms operate in two phases: we first need to determine the exponents of the product *R* and then its coefficients. The first phase is typically more expensive when the coefficients of *R* are small, but it becomes cheap for large coefficients, due to the fact that we may first reduce *P*, *Q*, *R* modulo a suitable prime. It is also customary to distinguish between the supersparse case in which the total degree of *R* is allowed to become huge and the normally sparse case in which the total degree remains small. In this paper, we mainly focus on the second problem, which is most important for practical applications.

In order to describe the complexity results, let us introduce some notations. Given a polynomial $P \in \mathbb{Z}[x_1, ..., x_n]$, we will write d_P for its total degree, t_P for its number of terms, s_P for the number of powers x_i^e that occur in its representation, and |P| for the maximal absolute of a coefficient. For instance, if $P = 3x_1^2x_2 - 20x_2x_3x_4 + x_4^4$, then we have $d_P = 4$, $t_P = 3$, $s_P = 6$, and |P| = 20. For our multiplication problem R = PQ, the degree $d := d_R = d_P + d_Q$ of the result is easily determined, but we usually only assume a bound $T \ge t_R$ with $T = O(t_R)$ for its number of terms.

It is interesting to keep track of the dependency of our running times on logarithmic factors in certain parameters, but it is also convenient to ignore less important logarithmic and sublogarithmic factors. We do this by introducing the notation

$$f = O^{\flat}(g) \iff f = O(g(\log(s_P s_O s_R |P||Q||R|))^{o(1)} (\log(dn))^{O(1)})$$

We also wish to compare the cost of our algorithms with the cost of multiplying dense univariate polynomials of approximately the same size. Given integers N, r > 1, we therefore also introduce the following two complexities:

- $M_N(r)$ stands for the cost of multiplying two non-zero polynomials in $\mathbb{Z}[u]/(u^r-1)$ under the assumption that the product *R* satisfies $|R| \leq N$.
- $M'_N(r)$ stands for the cost of multiplying two polynomials in $(\mathbb{Z}/N\mathbb{Z})[u]/(u^r-1)$.

We make the customary assumption that $M_N(r)/r$ and $M'_N(r)/r$ are non-decreasing as functions in r. By [14], one may take $M_N(r) = O(r \log N \log(r \log N))$. If r = O(N), then one also has $M'_N(r) = O(M_N(r))$, using Kronecker substitution [11].

One traditional approach for sparse polynomial multiplication is to evaluate *P*, *Q*, and *R* at 2*T* points in a geometric progression $(p_1^k, p_2^k, ..., p_n^k)$ modulo a sufficiently large prime number $\Pi \approx T p_n^d$, where p_i stands for the *i*-th prime number. In combination with the tangent Graeffe method [21, sections 5 and 7.2], this approach allows the exponents of *R* to be computed in time

$$O^{\flat}(\mathsf{M}'_{\Pi}(T)\log\Pi). \tag{1}$$

The coefficients can be recovered using fast Vandermonde system solving, in time

$$O^{\flat}(\mathsf{M}'_{N}(t)\log t),\tag{2}$$

where N = 2t |P| |Q| > 2|R| - 1. In our case when *d* is small, we usually have $\log \Pi = O^{\flat}(\log T)$, in which case (1) simplifies into $O^{\flat}(T (\log T)^3)$. The dependence of the complexity on *d* can be reduced using techniques from [26], among others.

The main results of this paper are two faster probabilistic algorithms. The shorter running times rely on two heuristics **HE** and **HC** that will be detailed in section 4. For any $\tau > \tau_{crit}$, we show (Theorem 6) that the exponents of *R* can be computed in time

$$6\tau M'_{\Pi}(T) + O^{\flat}((s_P + s_O + s_R)\log\Pi + (t_P + t_O)\log N + t_R n),$$
(3)

where $N = T^2 |P| |Q|$ and $\Pi = T p_n^d$ is prime. This algorithm is probabilistic of Monte Carlo type. Based on numerical evidence in section 3, we conjecture that $\tau_{crit} \approx 0.407265$. We also show (Theorem 4) that the coefficients may be computed in expected time

$$3\tau M_N(t_R) + O^{\flat}((s_P + s_Q + s_R)\log t_R + (t_P + t_Q + t_R)\log N),$$
(4)

using a probabilistic algorithm of Las Vegas type. In practice, when *d* is small and *n* not too large with respect to log *T*, the corrective terms in (3) are negligible and the cost reduces to $(6 \tau + o(1)) M'_{\Pi}(T)$. Similarly, the cost (4) usually simplifies to $(3 \tau + o(1)) M_N(t_R)$. If we also have $\Pi = o(N)$, then this means that the cost of the entire sparse multiplication becomes $(3 \tau + o(1)) M_N(t)$. Here we note that $M_N(t)$ also corresponds to the time needed to multiply two dense polynomials in $\mathbb{Z}[x]$, provided that the product *R* satisfies deg *R* < *t* and *t*|*R*| < *N*.

The proof of these bounds relies on the evaluation of *R* at three points of the form $(u^{\lambda_1},...,u^{\lambda_n})$ in algebras of the form $\mathbb{Z}[u]/(u^r-1)$, where $r = \lfloor \tau t \rfloor$. If τ is sufficiently large (namely $\tau > \tau_{\text{crit}}$ for some critical value) and we already know the exponents of *R*, then we show how to recover the coefficients with high probability. One interesting feature of our algorithm is that three evaluations are sufficient with high probability. A logarithmic number of evaluations is necessary when using the more obvious iterative approach for which every additional evaluation allows us to compute a constant fraction of the unknown coefficients (with high probability). Our algorithm is first explained with an example in section 2 and then in general in section 4.1. The probabilistic analysis is done in section 3. In section 4.2, we extend our approach to the computation of the exponents, using three additional evaluations. The last section 5 is devoted to variants and extensions of our approach, and further remarks.

The present paper works out an idea that was first mentioned in [21, section 6.6], in the context of general sparse interpolation. The application to polynomial multiplication is particularly suitable because of the low amortized cost of blackbox evaluations. The idea of using evaluations in (small) cyclic algebras has been used before in [2, 9, 31], but with a less optimal complexity. This approach also seems close to binning techniques that have recently been applied to compute sparse Fourier transforms [15, 30]; we plan to investigate this parallel in future work.

2. A GAME OF MYSTERY BALLS

Consider two sparse polynomials

$$P = xy^{5} + 3xy^{6}z - 2x^{8}y^{10} + x^{10}y^{14}z^{3}$$

$$Q = 2 + yz + 3x^{2}y^{4}z^{3}.$$



Figure 1. Playing the game of mystery balls. At every round, we remove the balls that ended up in a private box for at least one of the three throws.

Their product R = PQ is given by

$$R = 3x^{12}y^{18}z^6 + x^{10}y^{15}z^4 + 9x^3y^{10}z^4 + 3x^3y^9z^3 - 4x^{10}y^{14}z^3 + 3xy^7z^2 + 7xy^6z - 2x^8y^{11}z + 2xy^5 - 4x^8y^{10}.$$

Assume that the monomials $x^{12}y^8z^6$, $x^{10}y^{15}z^4$,... of *R* are known, but not the corresponding coefficients. Our aim is to determine *R* through its evaluations at "points" of the form $(x, y, z) = (u^{\alpha}, u^{\beta}, u^{\gamma})$ in $\mathbb{Z}[u]/(u^r-1)$ for suitable $\alpha, \beta, \gamma \in \mathbb{N}$ and lengths *r*. These evaluations are obtained by evaluating *P* and *Q* at the same points and multiplying the results in $\mathbb{Z}[u]/(u^r-1)$. In what follows, we will use three evaluation points.

Let us show how to turn the problem of computing the coefficients of *R* into a "game of mystery balls". At the start of the game, we have one numbered ball for each term of *R*:

$$R = \frac{\textcircled{0}}{3x^{12}y^{18}z^6} + \frac{\textcircled{0}}{x^{10}y^{15}z^4} + \frac{\textcircled{0}}{9x^3y^{10}z^4} + \frac{\textcircled{0}}{3x^3y^9z^3} + \underbrace{(-4)x^{10}y^{14}z^3}_{\textcircled{0}} + \underbrace{\textcircled{0}}_{3xy^7z^2} + \overbrace{7xy^6z}_{y^6z} + \underbrace{(-2)x^8y^{11}z}_{(-2)x^8y^{11}z} + \underbrace{2xy^5}_{y^5} + \underbrace{(-4)x^8y^{10}}_{\textcircled{0}}.$$

For each ball, say ①, the corresponding "mystery coefficient" 3 needs to be determined (it might be hidden inside the ball), whereas the corresponding exponents 12, 18, 6 are known (and stored in a table or painted on the ball). In fact, our game has three identical sets of balls, one for each of the three evaluation points. For each of these evaluation points, we also have a set of *r* boxes, labeled by $1, u, u^2, ..., u^{r-1}$.

Now consider the evaluation of *R* at a point as above, say at (x, y, z) = (u, u, u) in the ring $\mathbb{Z}[u]/(u^5-1)$. Then each term $\kappa x^a y^b z^c$ evaluates to a term κu^e with $e \in \{0, 1, 2, 3, 4\}$ and e = a + b + c modulo 5. In our game, we throw the corresponding ball into the box that is labeled by u^e . For instance, our first ball ① evaluates to 3u and goes into the box labeled by u. Our second ball ② evaluates to $1 u^4$ and goes into the box labeled by u^4 . Continuing this way, we obtain the upper left distribution in Figure 1. Now the complete evaluation of *R* at (x, y, z) = (u, u, u) in $\mathbb{Z}[u]/(u^5-1)$ gives

$$R(u, u, u) = 4 + 5u + 5u^{2} + 3u^{3} + u^{4} \pmod{u^{5} - 1}.$$

For each box, this means that we also know the sum of all coefficients hidden in the balls in that box. Indeed, in our example, the first box u^0 contains three balls (4), (6), and (8), with coefficients 3, 3, and -2 that sum up to 4. In Figure 1, we indicated these sums below the boxes. In round one of our game, we actually took our chances three times, by using the three evaluation points (u, u, u), (1, u, 1), and (1, 1, u) in $\mathbb{Z}[u]/(u^5-1)$, and throwing our balls accordingly. This corresponds to the top row in Figure 1.

Now we play our game as follows. If, in a certain round, a ball ends up alone in its box (we will also say that the ball has a private box), then the number below it coincides with the secret coefficient inside. At that point, we may remove the ball, as well as its copies from the two other throws, and update the numbers below accordingly. In round one of our running example, ball 2 ends up in a box of its own for our first throw. Similarly, the balls 6 and 7 both have private boxes for the second throw. Ball 6 also has a private box for the third throw. Removing the balls ②, ⑥, and ⑦ from the game, we obtain the second row in Figure 1. We also updated the numbers below the boxes: for every box, the number below it still coincides with the sum of the mystery coefficients inside the balls inside that box. Now that the balls (2), (6), and (7) have been removed, we observe that balls ③ and ⑩ have private boxes in their turn. We may thus determine their mystery coefficients and remove them from the game as well. This brings us to round three of our game and the third row in Figure 1. Going on like this, we win our game when all balls eventually get removed. We lose whenever there exists a round in which there are still some balls left, but all non-empty boxes contain at least two balls. In our example, we win after five rounds.

Remark 1. When implementing a computer program to play the game, we maintain a table that associates to each ball its exponents and the three boxes where it ended up for the three throws. Conversely, for each box, we maintain a linked list with all balls inside that box. We finally maintain a list with balls inside a private box, and which are about to be removed. In this way, the total amount of work that needs to be done in each round remains proportional to the number of balls that are removed instead of the total number of boxes.

Remark 2. Playing our game in several "rounds" is convenient for the probabilistic analysis in section 3 below. But the order in which balls in private boxes are removed actually does not matter, as long as we remove all balls in private boxes. Assume for instance that we win our game and that we replay it by removing balls in another order. Assume for contradiction that a ball *B* does not get removed in our modified game and choose *B* in such a way that the round *i* in which it gets removed in the original game

is minimal. Then we observe that all balls that were removed before round *i* in the original game also get removed in the modified version, eventually. When this happens, *B* is in a private box for one of the throws: a contradiction.

3. ON OUR PROBABILITY OF WINNING THE GAME

Have we been lucky in our example with 3 throws of 10 balls in 5 boxes? For the probabilistic analysis in this section, we will assume that our throws are random and independent. We will do our analysis for three throws, because this is best, although a similar analysis could be carried out for other numbers of throws. From now on, we will assume that we have *t* balls and $r = \tau t$ boxes.

The experiment of throwing *t* balls in *r* boxes has widely been studied in the literature about hash tables [7, Chapter 9]. For a fixed ball, the probability that all other t-1 balls end up in another box is given by

$$p_1 = \left(1 - \frac{1}{r}\right)^{t-1} = e^{(t-1)\log\left(1 - \frac{1}{\tau t}\right)} = e^{-\frac{1}{\tau} + O\left(\frac{1}{t}\right)} = e^{-\frac{1}{\tau}} + O\left(\frac{1}{t}\right).$$

More generally, for any fixed $k \ge 1$, the probability that k-1 other balls end up in the same box and all the others in other boxes is given by

$$p_{k} = {\binom{t-1}{k-1}} \frac{1}{r^{k-1}} \left(1 - \frac{1}{r}\right)^{t-k}$$

= $\frac{t^{k-1} + O(t^{k-2})}{(k-1)!} \cdot \frac{1}{\tau^{k-1}t^{k-1}} \left(e^{-\frac{1}{\tau}} + O\left(\frac{1}{t}\right)\right)$
= $\frac{e^{-\frac{1}{\tau}}}{(k-1)!\tau^{k-1}} + O\left(\frac{1}{t}\right).$

Stated otherwise, we may expect with high probability that approximately $p_1 t$ balls end up in a private box, approximately $p_2 t$ balls inside a box with one other ball, and so on.

This shows how we can expect our balls to be distributed in the first round of our game and at the limit when *t* gets large. Assume more generally that we know the distribution $(p_{i,k})_{k \in \mathbb{N}}$ in round *i* and let us show how to determine the distribution $(p_{i+1,k})_{k \in \mathbb{N}}$ for the next round. More precisely, assume that $p_{i,k}(t + O(1))$ is the expected number of balls in a box with *k* balls in round *i*, where we start with

$$p_{1,k} = \frac{\mathrm{e}^{-\frac{1}{\tau}}}{(k-1)!\,\tau^{k-1}}.$$

Setting

$$\sigma_i = p_{i,1} + p_{i,2} + \cdots,$$

we notice that $1 = \sigma_1 > \sigma_2 > \sigma_3 > \cdots$, where $(\sigma_{i+1} - \sigma_i) t$ stands for the expected number of balls that are removed during round *i*.

$p_{i,k}$	k=1	2	3	4	5	6	7	σ_i
i = 1	0.13534	0.27067	0.27067	0.18045	0.09022	0.03609	0.01203	1.00000
2	0.06643	0.25063	0.18738	0.09340	0.03491	0.01044	0.00260	0.64646
3	0.04567	0.21741	0.13085	0.05251	0.01580	0.00380	0.00076	0.46696
4	0.03690	0.18019	0.08828	0.02883	0.00706	0.00138	0.00023	0.34292
5	0.03234	0.13952	0.05443	0.01416	0.00276	0.00043	0.00006	0.24371
6	0.02869	0.09578	0.02811	0.00550	0.00081	0.00009	0.00001	0.15899
7	0.02330	0.05240	0.01033	0.00136	0.00013	0.00001	0.00000	0.08752
8	0.01428	0.01823	0.00193	0.00014	0.00001	0.00000	0.00000	0.03459
9	0.00442	0.00249	0.00009	0.00000	0.00000	0.00000	0.00000	0.00700
10	0.00030	0.00005	0.00000	0.00000	0.00000	0.00000	0.00000	0.00035
11	0.00000	0.00000	0.00000	0.00000	0.00000	0.00000	0.00000	0.00000

Table 1. The probability distributions $(p_{i,k})_{k \in \mathbb{N}}$ in rounds i = 1, ..., 11 for $\tau = 1/2$.

Now let us focus on the first throw in round *i* (the two other throws behave similarly, since they follow the same probability distribution). There are $p_{i,1}t$ balls that are in a private box for this throw. For each of the remaining balls, the probability π_i that it ended up in a private box for at least one of the two other throws is

$$\pi_i = \left(2 - \frac{p_{i,1}}{\sigma_i}\right) \frac{p_{i,1}}{\sigma_i}.$$

The probability that a box with $k \ge 2$ balls becomes one with *j* balls in the next round is therefore given by

$$\lambda_{j,k} = \binom{k}{j} \pi_i^{k-j} \left(1 - \pi_i\right)^j.$$

For all $j \ge 1$, this yields

$$p_{i+1,j} = \sum_{k \ge \max(2,j)} \frac{j}{k} \lambda_{j,k} p_{i,k}$$

If σ_i tends to zero for large *i* and *t* gets large, then we win our game with high probability. If σ_i tends to a limit $\ell \in (0, 1)$, then we will probably lose and end up with approximately ℓt balls that can't be removed (for each of the three throws).

We have not yet been able to fully describe the asymptotic behavior of the distribution $(p_{i,k})_{k \in \mathbb{N}}$ for $i \to \infty$, which follows a non-linear dynamics. Nevertheless, it is easy to compute reliable approximations for the coefficients $p_{i,k}$ using interval or ball arithmetic [17]; for this purpose, it suffices to replace each coefficient $p_{i,k}$ in the tail of the distribution (i.e. for large k) by the interval $[0, p_{1,k}]$. Tables 1, 2, and 3 show some numerical data that we computed in this way (the error in the numbers being at most $0.5 \cdot 10^{-5}$). Our numerical experiments indicate that the "phase change" between winning and losing occurs at a critical value τ_{crit} with

$$0.407264 < \tau_{\rm crit} < 0.407265.$$

Table 1 shows what happens for $\tau = 1/2$: until the seventh round, a bit less than half of the balls get removed at every round. After round eight, the remaining balls are removed at an accelerated rate. For $\tau = 1/3$, the distributions $(p_{i,k})_{k \in \mathbb{N}}$ numerically tend to a non-zero limit distribution $(p_{\infty,k})_{k \in \mathbb{N}}$ with $\sigma_{\infty} := p_{\infty,1} + p_{\infty,2} + \cdots \approx 0.78350$. In Table 3, we show some of the distributions in round ten, for τ near the critical point τ_{crit} . We also computed an approximation of the limit distribution at the critical point itself.

$p_{i,k}$	k = 1	2	3	4	5	6	7	σ_i
i = 1	0.04979	0.14936	0.22404	0.22404	0.16803	0.10082	0.05041	1.00000
2	0.01520	0.16294	0.22068	0.19925	0.13493	0.07310	0.03300	0.85795
3	0.00579	0.16683	0.21802	0.18994	0.12410	0.06487	0.02826	0.81315
4	0.00238	0.16826	0.21676	0.18616	0.11991	0.06179	0.02584	0.79590
5	0.00101	0.16883	0.21620	0.18457	0.11818	0.06053	0.02584	0.78878
6	0.00043	0.16907	0.21596	0.18389	0.11744	0.06000	0.02555	0.78577
7	0.00019	0.16918	0.21585	0.18360	0.11713	0.05978	0.02542	0.78448
8	0.00008	0.16922	0.21581	0.18347	0.11699	0.05968	0.02535	0.78392
9	0.00003	0.16924	0.21579	0.18342	0.11693	0.05964	0.02535	0.78368
10	0.00001	0.16925	0.21578	0.18340	0.11691	0.05962	0.02534	0.78358
11	0.00001	0.16925	0.21577	0.18339	0.11690	0.05961	0.02533	0.78353
12	0.00000	0.16925	0.21577	0.18338	0.11690	0.05961	0.02533	0.78351

Table 2. The probability distributions $(p_{i,k})_{k \in \mathbb{N}}$ in rounds i = 1, ..., 11 for $\tau = 1/3$.

<i>p</i> _{10,k}	k=1	2	3	4	5	6	7	σ_{10}
$\tau = 0.333$	0.00001	0.16892	0.21573	0.18368	0.11729	0.05992	0.02551	0.78447
$\tau = 0.400$	0.00190	0.20779	0.16840	0.09099	0.03687	0.01195	0.00323	0.52207
$\tau = 0.405$	0.00258	0.20592	0.15856	0.08140	0.03134	0.00965	0.00248	0.49260
$\tau = 0.407$	0.00290	0.20479	0.15429	0.07750	0.02919	0.00880	0.00221	0.48027
$\tau = 0.410$	0.00346	0.20266	0.14752	0.07159	0.02606	0.00759	0.00184	0.46118
$\tau = 0.420$	0.00601	0.19090	0.12180	0.05181	0.01653	0.00422	0.00090	0.39235
$\tau = 0.450$	0.01841	0.09767	0.03137	0.00672	0.00108	0.00014	0.00001	0.15541
$\tau = 0.500$	0.00030	0.00005	0.00000	0.00000	0.00000	0.00000	0.00000	0.00035
$p_{10000,k}, \tau_{\rm crit}$	0.00000	0.18338	0.11551	0.04851	0.01528	0.00385	0.00081	0.36751

Table 3. The probability distributions $(p_{10,k})_{k \in \mathbb{N}}$ in round 10 for various τ as well as an approximation of the limit distribution for $\tau = \tau_{crit}$ by taking the distribution in round 10000 for $\tau \approx 0.407264 \approx \tau_{crit}$.

For $\tau < \tau_{\rm crit}$, we note that reliable numerical computations can be turned into an actual proof that we lose with high probability. Indeed, assume that $\varepsilon := p_{i,1} = o(1)$ gets very small for some *i*, whereas $\sigma_i^{-1} = O(1)$ remains bounded (for instance, in Table 2, we have $p_{i,1} < 10^{-5}$ and $\sigma_i = 0.78351$ for i = 12). Then $\pi_i = (2 + O(\varepsilon)) \frac{\varepsilon}{\sigma_i} = O(\varepsilon)$ also gets very small and

$$p_{i+1,1} = \sum_{k \ge 2} \pi_i^{k-1} (1 - \pi_i) p_{i,k}$$
$$= p_{i,2} \pi_i + O(\varepsilon^2)$$
$$= 2 \frac{p_{i,2}}{\sigma_i} \varepsilon + O(\varepsilon^2)$$
$$p_{i+1,k} = p_{i,k} + O(\varepsilon), \quad k \ge 2.$$

If $2p_{i,2}$ happens to be ν times smaller than σ_i for some fixed $\nu > 1$ (for instance, in Table 2, we actually have $4p_{i,2} < \sigma_i$ for i = 12), then a standard contracting ball type argument can be used to prove that $p_{i',1}$ decreases to zero with geometric speed for $i' \ge i$, while $\sigma_{i'}$ remains bounded away from zero.

N _{i,k}	k = 1	2	3	4	5	6	7	Σ_i
i = 1	13438	27132	27027	18072	9075	3516	1260	100000
2	6577	25344	18576	9360	3575	990	259	64793
3	4524	22004	13149	5196	1535	354	84	46854
4	3649	18310	8904	2808	665	156	14	34506
5	3247	14190	5406	1464	295	24	0	24626
6	2849	9892	2823	556	65	6	0	16191
7	2327	5522	1071	124	15	0	0	9059
8	1501	1946	225	12	5	0	0	3689
9	487	256	18	0	0	0	0	761
10	34	6	0	0	0	0	0	40
11	0	0	0	0	0	0	0	0

Table 4. Carrying out a random simulation of our game for t = 100000 and $\tau = \frac{1}{2}$. The table shows the number $N_{i,k}$ of balls that are in a box with *k* balls in round *i* (for the first throw). The last column also shows the sum $\Sigma_i = N_{i,1} + N_{i,2} + \cdots$.

Conversely, given $\tau > \tau_{crit}$, it seems harder to prove in a similar way that we win. Nevertheless, for any $\varepsilon > 0$, reliable computations easily allow us to determine some round *i* with $\sigma_i < \varepsilon$. For instance, for $\tau = \frac{1}{2}$ and $\varepsilon = 10^{-5}$, we may take i = 11. This is good enough for practical purposes: for $t = 10000 \ll \varepsilon^{-1}$, it means that we indeed win with high probability. Here we also note that a large number of rounds are generally necessary to win when τ approaches the critical value τ_{crit} . For instance, for $\tau = 0.42$, we need to wait until round i = 29 to get $\sigma_i < 10^{-5}$. Nevertheless, after a certain number of rounds, it seems that σ_i always converges to zero with superlinear speed.

In Table 4, we conclude with the result of a computer simulation in which we played our game with t = 100000 and $\tau = \frac{1}{2}$. As one can see, the results are close to the theoretically expected ones from Table 1.

Remark 3. Our game of mystery balls readily generalizes to different numbers of throws and different numbers of boxes for each throw. However, if our aim is to take the total number of boxes as small as possible, then computer experiments suggest that using three throws with the same number of boxes is optimal. For simplicity, we therefore restricted ourselves to this case, although it should be easy to extend our analysis to a more general setting.

4. MULTIPLYING SPARSE POLYNOMIALS

Let us now turn to the general problem of multiplying sparse polynomials. We will focus on the multiplication R = PQ of integer polynomials $P, Q \in \mathbb{Z}[x_1, ..., x_n]$ in at least two variables. We define *d* to be the total degree of *R* and assume that we have a bound *T* for the number of terms of *R*.

As explained in the introduction, we proceed in two phases: we first determine the exponents of the unknown product *R*. This part is probabilistic of Monte Carlo type, where we tolerate a rate of failure $\varepsilon > 0$ that is fixed in advance. In the second phase, we determine the unknown coefficients, using a probabilistic algorithm of Las Vegas type. In this section, we start with the second phase, which has already been explained on an example in section 2.

Algorithm 1

Input: $P, Q \in \mathbb{Z}[x_1, ..., x_n]$ and $e_1, ..., e_t \in \mathbb{N}^n$ with $PQ \in \mathbb{Z}x^{e_1} + \cdots + \mathbb{Z}x^{e_t}$ **Output:** the product PQ, with high probability (Las Vegas) **Assume:** $n \ge 2$ and $t \ge 6$

- 1. For a fixed $\tau > \tau_{\text{crit}}$, let $r := \lfloor \tau t \rfloor$.
- 2. Let $\lambda_1, \lambda_2, \lambda_3 \in \{0, ..., r-1\}^n$ be random vectors that are pairwise non-collinear modulo *r*.
- 3. Compute $P_i = P(u^{\lambda_{i,1}}, \dots, u^{\lambda_{i,n}})$ and $Q_i = Q(u^{\lambda_{i,1}}, \dots, u^{\lambda_{i,n}})$ in $\mathbb{Z}[u]/(u^r-1)$, for i=1,2,3.
- 4. Multiply $R_i := P_i Q_i$ in $\mathbb{Z}[u] / (u^r 1)$, for i = 1, 2, 3.
- 5. Let $J := \{1, \ldots, t\}$.
- 6. While there exist $i \in \{1, 2, 3\}$ and $j \in J$ with $\lambda_i \cdot e_j \neq \lambda_i \cdot e_{j'}$ for all $j' \in J \setminus \{j\}$, do
 - a. Let c_i be the coefficient of $u^{\lambda_i \cdot e_j}$ in R_i .
 - b. For $i' \in \{1, 2, 3\}$, replace $R_i := R_i c_i u^{\lambda_i \cdot e_i}$.
 - c. Replace $J := J \setminus \{j\}$.
- 7. Return $c_1 x^{e_1} + \cdots + c_t x^{e_t}$ if $J = \emptyset$ and "failed" otherwise.

4.1. Determination of the coefficients

Assume that our product R = PQ has t terms, so that $R = c_1 x^{e_1} + \cdots + c_t x^{e_t}$ for certain $c_1, \dots, c_t \in \mathbb{Z}$ and $e_1, \dots, e_t \in \mathbb{N}^n$, where $x^{e_i} = x_1^{e_{i,1}} \cdots x_n^{e_{i,n}}$ for $i = 1, \dots, t$. It is obvious how to generalize the algorithm from section 2 to this case: for some fixed $\tau > \tau_{\text{crit}}$, we distribute "our t balls" over $r = \lfloor \tau t \rfloor$ boxes, through the evaluation of R at three points $(u^{\lambda_{i,1}}, \dots, u^{\lambda_{i,n}})$ in $\mathbb{Z}[u]/(u^r-1)$ for i = 1, 2, 3 and $\lambda_1, \lambda_2, \lambda_3 \in \mathbb{Z}^n$. The vectors $\lambda_1, \lambda_2, \lambda_3$ are essentially chosen at random, but it is convenient to take them pairwise non-collinear modulo r, so as to avoid any "useless throws". We assume the following heuristic:

HE. For random vectors λ_1 , λ_2 , λ_3 as above each of the three throws randomly distributes the balls over the boxes, and the three distributions are independent.

We then play our game of mystery balls as usual, which yields the coefficients $c_1, ..., c_t$ if we win and only a subset of these coefficients if we lose. In view of Remark 2, this leads to Algorithm 1.

THEOREM 4. Assume heuristic **HE**. Let $\tau > \tau_{crit}$ with $\tau \leq 1$ and $N = t_R^2 |P| |Q|$. Then Algorithm 1 is correct and runs in time

$$3 \tau M_N(t_R) + O^{\flat}((s_P + s_O + s_R) \log t_R + (t_P + t_O + t_R) \log N).$$

Proof. The correctness of the algorithm has been explained in section 2. As to the running time, we first note that none of the integer coefficients encountered during our computation exceeds *N* in absolute value. Now steps 1 and 2 have negligible cost and the running time for the remaining steps is as follows:

• In step 3, for every term cx^e in *P* or *Q* and every $i \in \{1, 2, 3\}$, we first have to compute $\lambda_i \cdot e = \lambda_{i,1}e_1 + \cdots + \lambda_{i,n}e_n$ modulo *r*. Since we only have to accumulate $\lambda_{i,j}e_j$ when $e_i \neq 0$, this can be done in time $O^{\flat}((s_P + s_Q) \log r)$. We next have to add the coefficients of all terms that end up in the same box, which amounts to $O(t_P + t_Q)$ additions of cost $O((t_P + t_Q) \log N)$.

- In step 4, we do three multiplications of cost $M_N(r)$ each. Since $M_N(r)/r$ is nondecreasing, the cost of these multiplications is bounded by $3 \tau M_N(t_R)$.
- In steps 5 and 6, we play our game of mystery balls, where *J* stands for the set of ball that are still in play. Whenever ball *j* ends up in a private box for throw number *i*, we have to determine where this ball landed for the other throws, by computing $\lambda_{i'} \cdot e_j$ modulo *r* for $i' \neq i$. We then have to update the numbers below the corresponding boxes, which corresponds to setting $R_i := R_i c_j u^{\lambda_i \cdot e_j}$ in step 6b. Since this eventually has to be done for each of the *t* balls, step 6 takes $O(s_R \log r + t_R \log N)$ bit-operations, using a similar analysis as for step 3.

Let us finally investigate bookkeeping costs that are implicit in our description of the algorithm. Above all, we have to maintain the linked lists with balls inside each box (see Remark 1). This can be done in time

$$O\left(\sum_{k \ge 1} k p_{1,k} T\right) = O\left(\sum_{k \ge 1} \frac{k}{(k-1)! \tau^{k-1}} e^{-1/\tau} T\right) = O(T).$$

The other implicit costs to maintain various tables are also bounded by O(T).

4.2. Determination of the exponents

In [21], we surveyed several strategies for computing the exponents of the product *R*. Most of the approaches from sections 4, 6, and 7 of that paper can be adapted to the present setting. We will focus on a probabilistic strategy that we expect to be one of the most efficient ones for practical purposes (a few variants will be discussed in section 5).

For $i = 1, 2, ..., \text{let } p_i$ be the *i*-th prime number and let $B = p_n^d$. We let Π be a fixed prime number with $\Pi \ge BT/\varepsilon$ (for practical implementations, we may also take Π to be a product of prime numbers that fit into machine words, and use multi-modular arithmetic to compute modulo Π). For some fixed $\tau > \tau_{\text{crit}}$, we again use $r = \lfloor \tau T \rfloor$ boxes, and evaluate P, Q, R over the ring $(\mathbb{Z}/\Pi\mathbb{Z})[u]/(u^r-1)$. This time, we use six evaluation points of the form $(u^{\lambda_{i,1}}, \ldots, u^{\lambda_{i,n}})$ and $(p_1 u^{\lambda_{i,1}}, \ldots, p_n u^{\lambda_{i,n}})$ for i = 1, 2, 3, where the $\lambda_1, \lambda_2, \lambda_3$ are chosen at random and pairwise non-collinear modulo r.

Now consider a term $c x_1^{k_1} \cdots x_n^{k_n}$ of R. Its evaluation at $(u^{\lambda_{i,1}}, \dots, u^{\lambda_{i,n}})$ is $c u^e$, where $e = \lambda_{i,1}k_1 + \dots + \lambda_{i,n}k_n$ modulo r. Meanwhile, its evaluation at $(p_1u^{\lambda_{i,1}}, \dots, p_nu^{\lambda_{i,n}})$ is $\tilde{c} u^e$ with $\tilde{c} = p_1^{k_1} \cdots p_n^{k_n} c$. If there is no other term that evaluates to an expression of the form $c' u^e$ at $(u^{\lambda_{i,1}}, \dots, u^{\lambda_{i,n}})$, then the same holds for the evaluation at $(p_1u^{\lambda_{i,1}}, \dots, p_nu^{\lambda_{i,n}})$. Consequently, the unique representative $q \in \{0, \dots, \Pi - 1\}$ of the quotient \tilde{c}/c in $\mathbb{Z}/\Pi \mathbb{Z}$ coincides with $p_1^{k_1} \cdots p_n^{k_n}$ (the quotient is well defined with high probability). From this, we can determine the exponents k_1, \dots, k_n by factoring q. As additional safeguards, we also check that $q \leq B$, that all prime factors of q are in $\{p_1, \dots, p_n\}$, and that $e = \lambda_{i,1}k_1 + \cdots + \lambda_{i,n}k_n$ modulo r.

Conversely, assume that there are at least two terms of *R* that evaluate to an expression of the form $c' u^e$ at $(u^{\lambda_{i,1}}, ..., u^{\lambda_{i,n}})$. Let *c* and \tilde{c} now be the coefficients of u^e in $R(u^{\lambda_{i,1}}, ..., u^{\lambda_{i,n}})$ and $R(p_1 u^{\lambda_{i,1}}, ..., p_n u^{\lambda_{i,n}})$. Then the quotient \tilde{c}/c is essentially a random element in $\mathbb{Z}/\Pi\mathbb{Z}$ (see the heuristic **HC** below for more details), so its unique representative in $\{0, ..., \Pi-1\}$ is higher than *B* with probability $1 - \varepsilon/T$. This allows our algorithm to detect that we are dealing with colliding terms; for the O(T) quotients that we need to consider the probability of failure becomes $1 - (1 - \varepsilon/T)^{O(T)} = O(\varepsilon)$.

Algorithm 2

Input: $P, Q \in \mathbb{Z}[x_1, ..., x_n]$ and a bound $T \ge t_{PQ}$

Output: the exponents of the product *PQ*, with high probability (Monte Carlo) **Assume:** $n \ge 2$ and $t \ge 6$

- 1. For a fixed $\tau > \tau_{\text{crit}}$, let $r := \lfloor \tau t \rfloor$, $B := p_n^d$, and $\Pi \ge \lceil BT/\varepsilon \rceil$ prime.
- 2. Let $\lambda_1, \lambda_2, \lambda_3 \in \{0, ..., r-1\}^n$ be random vectors that are pairwise non-collinear modulo *r*.
- 3. Compute the reductions $\overline{P}, \overline{Q} \in (\mathbb{Z}/\Pi\mathbb{Z})[x_1, \dots, x_n]$ of P, Q modulo Π .
- 4. Let v_1, \ldots, v_n be random invertible elements in $\mathbb{Z}/\Pi \mathbb{Z}$. Replace $\bar{P} := \bar{P}(v_1 x_1, \ldots, p_n x_n)$ and $\bar{Q} := \bar{Q}(v_1 x_1, \ldots, p_n x_n)$. Compute $\tilde{P} := \bar{P}(p_1 x_1, \ldots, p_n x_n)$ and $\tilde{Q} := \bar{Q}(p_1 x_1, \ldots, p_n x_n)$ in $(\mathbb{Z}/\Pi \mathbb{Z})[x_1, \ldots, x_n]$.
- 5. Compute the evaluations \bar{P}_i , \bar{Q}_i , \tilde{P}_i , \tilde{Q}_i of \bar{P} , \bar{Q} , \tilde{P} , \tilde{Q} at $(u^{\lambda_{i,1}}, \dots, u^{\lambda_{i,n}})$ for i = 1, 2, 3.
- 6. Multiply $\overline{R}_i := \overline{P}_i \overline{Q}_i$ and $\widetilde{R}_i := \widetilde{P}_i \widetilde{Q}_i$ in $\mathbb{Z}[u] / (u^r 1)$, for i = 1, 2, 3.
- 7. Let $\Omega := \{(i,e) \in \{1,2,3\} \times \{1,\ldots,r\} : \overline{R}_{i,e} \neq 0\}$ and $E := \emptyset$. For all $(i,e) \in \Omega$, compute the preimage $q_{i,e} \in \{0,\ldots,\Pi-1\}$ of $\overline{R}_{i,e}/\overline{R}_{i,e}$. For all $(i,e) \in \Omega$, try factoring $q_{i,e} = p_1^{k_1} \cdots p_n^{k_n}$ whenever $q_{i,e} \leq B$.
- 8. While there exist $(i, e) \in \Omega$ with $q_{i,e} = p_1^{k_1} \cdots p_n^{k_n}$, $k_1 + \cdots + k_n \leq d$, and $k \cdot \lambda_i = e$, do
 - a. Let *c* and \tilde{c} be the coefficients of $u^{\lambda_i \cdot k}$ in \bar{R}_i and \tilde{R}_i .
 - b. For $i' \in \{1, 2, 3\}$, replace $\bar{R}_i := \bar{R}_i c u^{\lambda_i \cdot k}$ and $\tilde{R}_i := \tilde{R}_i \tilde{c} u^{\lambda_i \cdot k}$.
 - c. Also update $q_{i',e'} := \tilde{R}_{i,e'} / \bar{R}_{i,e'}$ and its factorization if $\bar{R}_{i,e'} \neq 0$ for $e' = \lambda_{i'} \cdot k$.
 - d. Replace $\Omega := \Omega \setminus \{(i', \lambda_{i'} \cdot k) : i' = 1, 2, 3\}$ and $E := E \cup \{k\}$.
- 9. Return *E* if $\Omega = \emptyset$ and "failed" otherwise.

Using the above technique, the three additional evaluations at $(p_1 u^{\lambda_{i,1}}, ..., p_n u^{\lambda_{i,n}})_{i=1,2,3}$, allow us to determine which balls end up in a private box in our game of mystery balls. Moreover, since we can determine the corresponding exponents, we can also find where these balls landed for the two other throws. This allows us to play our game modulo minor modifications. Besides maintaining the numbers below the boxes for the first three throws, we also maintain the corresponding numbers for the evaluations at $(p_1 u^{\lambda_{i,1}}, ..., p_n u^{\lambda_{i,n}})_{i=1,2,3}$. For every round of the game, the same technique then allows us to determine which balls have private boxes, and iterate.

In our probabilistic analysis, it is important that the quotients \tilde{c}/c are essentially random elements in $\mathbb{Z}/\Pi\mathbb{Z}$ in case of collisions. This assumption might fail when the coefficients of *P* and *Q* are special (e.g. either zero or one). Nevertheless, it becomes plausible after a change of variables $x_i \mapsto v_i x_i$, i = 1, ..., n, where $v_1, ..., v_n$ are random invertible elements in $\mathbb{Z}/\Pi\mathbb{Z}$. Let us formulate this as our second heuristic:

HE. For random vectors $\lambda_1, \lambda_2, \lambda_3$ and after a random change of variables $x_i \mapsto v_i x_i$ (i = 1, ..., n), the quotients \tilde{c}/c as above are uniformly distributed over $\mathbb{Z}/\Pi\mathbb{Z}$, and the distributions for different quotients are independent.

Algorithm 2 summarizes our method, while incorporating the random change of variables.

LEMMA 5. Given a number $q \in \{0, ..., \Pi - 1\}$ with distinct prime factors, it takes

 $O^{\flat}(n + s \log \Pi)$

bit operations to determine the existence of a prime factorization $q = p_1^{k_1} \cdots p_n^{k_n}$ with $k_1 + \cdots + k_n \leq d$, and to compute it in case there is.

Proof. We first determine the indices k with $k_j \neq 0$ using a divide and conquer technique. At the top level, we start with the remainder g of the division of q by $p_1 \cdots p_n$. We next compute $g_1 = \gcd(g, p_1 \cdots p_{\lfloor n/2 \rfloor})$ and $g_2 = \gcd(g, p_{\lfloor n/2 \rfloor+1} \cdots p_n)$. If $g_1 \neq 1$, then we go on with the computation of $g_{1,1} = \gcd(g_1, p_1 \cdots p_{\lfloor n/4 \rfloor})$ and $g_{1,2} = \gcd(g_1, p_{\lfloor n/4 \rfloor+1} \cdots p_{\lfloor n/2 \rfloor})$, and similarly for g_2 . We repeat this dichotomic process until we have found all prime factors of q. For each of the s prime factors p_j of q, we next compute $p_j^{k_j} = \gcd(q, p_j^d)$ and $k_j = \log p_j^{k_j} / \log p_j$. The total running time of this algorithm is bounded by $O(n \log^3 n + s \log \Pi \log \log \Pi) = O^{\flat}(n + s \log \Pi)$.

THEOREM 6. Assume the heuristics **HE** and **HC**. Let $\tau > \tau_{crit}$ with $\tau \leq 1$, $N = T^2 |P| |Q|$, and $\Pi = p_n^d T$. Then Algorithm 2 is correct and runs in time

 $6 \tau M'_{\Pi}(T) + O^{\flat}((s_P + s_Q + s_R) \log \Pi + (t_P + t_Q) \log N + t_R n).$

Proof. We have already explained why our algorithm returns the correct answer with probability $1 - O(\varepsilon)$. The complexity analysis for steps 5, 6 and 8b is similar as the one for Algorithm 1. The running time for the other steps is as follows:

- The reductions of *P* and *Q* modulo Π can be computed in time $O^{\flat}((t_P + t_Q) \log N)$, in step 3.
- In step 4, we have to compute p_i^e modulo Π for every power x_i^e occurring in the representation of *P* or *Q*. Using binary powering, such a power can be computed in time $O^{\flat}(\log d \log \Pi) = O^{\flat}(\log \Pi)$. The total cost of this step is therefore bounded by $O^{\flat}((s_P + s_Q) \log \Pi)$.
- In steps 7 and 8c, we have already shown that one factorization can be done in time O^b(n+slog Π). Altogether, the cost of these steps is therefore bounded by O^b(t_Rn+s_Rlog Π).

5. VARIANTS AND FURTHER EXPERIMENTS

5.1. Supersparse polynomials

In section 4.2, we have described an efficient algorithm for the case when the total degree *d* is small. This indeed holds for most practical applications, but it attractive to also study the case when our polynomials are "truly sparse" with potentially large exponents. This is already interesting for univariate polynomials, a case that we also did not consider so far. Modulo the technique of Kronecker substitution [21, Section 7.1], it actually suffices to consider the univariate case. For simplicity, let us restrict ourselves to this case. When p_n^d gets moderately large, it can also be interesting to consider the incremental approach from [20] and [21, Section 7.3].

One first observation in the univariate case is that we can no longer take the same number of boxes *r* for our three throws. Next best is to take $r_i = 2\lceil \tau t/2 \rceil + i$ boxes for our *i*-th throw, where i = 1, 2, 3. By construction this ensures that r_1 , r_2 , and r_3 are pairwise coprime. If the exponents of *R* are large, then it is also reasonable to assume that our heuristic **HE** still holds.

For the efficient determination of the exponents, let $\Pi \ge dT/\varepsilon$. As before, we may take Π to be prime or a product of prime numbers that fit into machine words. Following Huang [26], we now evaluate both $\overline{R} = \overline{P} \overline{Q}$ and $x \overline{R}' = x (\overline{P}' \overline{Q} + \overline{P} \overline{Q}')$ at u in $(\mathbb{Z}/\Pi\mathbb{Z})[u]/(u^{r_i}-1)$ for i=1,2,3. Any term cx^e of \overline{R} then gives rise to a term $\tilde{c}x^e$ of $x\overline{R}'$ with $\tilde{c} = ec$, so we can directly read off e from the quotient \tilde{c}/c . Modulo the above changes, this allows us to proceed as in Algorithm 2. One may prove in a similar way as before that the bit complexity of determining the exponents in this way is bounded by

 $9 \tau M'_{\Pi}(T) + O^{\flat}((s_P + s_O + s_R) \log t_R + (t_P + t_O + t_R) \log (\Pi N)).$

The computation of the coefficients can be done in time

$$3 \tau M_N(t_R) + O^{\flat}((s_P + s_Q + s_R) \log t_R + (t_P + t_Q + t_R) \log N).$$

5.2. Other rings of coefficients

Rational coefficients. Using the combination of modular reduction and rational number reconstruction [11, Chapter 5], the new algorithms generalize in a standard way to polynomials with rational coefficients.

Complex numbers. Given a fixed working precision p, it is also possible to use coefficients in \mathbb{C} , while using a fixed point number representation. Provided that all coefficients have the same order of magnitude, the floating point case can be reduced to this case. Indeed, the reductions modulo $u^r - 1$ are remarkably stable from a numerical point of view, and we may use FFT-multiplication in $\mathbb{C}[u]/(u^r - 1)$. Algorithm 2 can also be adapted, provided that $2^p \gg \lceil BT/\epsilon \rceil$.

Finite fields. Our algorithms adapt in a straightforward way to coefficients in a finite field of sufficiently large characteristic. If the characteristic is moderately large (e.g. of the size of a machine word), then one may keep Π small in Algorithm 2 by using the incremental technique from [20] and [21, Section 7.3]. Over finite fields \mathbb{F}_q of small characteristic, one needs to use other techniques from [21].

Instead of taking our three additional evaluation points of the form $(p_1 u^{\lambda_{i,1}},...,p_n u^{\lambda_{i,n}})$, we may for instance take them of the form $(\omega u^{\lambda_{i,1}}, \omega^{d+1} u^{\lambda_{i,2}},..., \omega^{(d+1)^{n-1}} u^{\lambda_{i,n}})$, where ω is a primitive root of unity of large smooth order (this may force us to work over an extension field; alternatively, one may use the aforementioned incremental technique and roots ω of lower orders). Thanks to the smoothness assumption, discrete logarithms of powers of ω can be computed efficiently using Pohlig–Hellman's algorithm. This allows us to recover exponents $k_1 \leq d,...,k_n \leq d$ from quotients of the form $\tilde{c}/c = \omega^{k_1+k_2(d+1)+\cdots+k_n(d+1)^{n-1}}$.

General rings. Finally, it is possible to use coefficients in a general ring \mathbb{A} , in which case complexities are measured in terms of the number of operations in \mathbb{A} . For rings of sufficiently large characteristic, one may directly adapt the algorithms from section 4. For rings of small characteristic, it is possible to generalize the techniques from the finite field case.

5.3. Other operations

The techniques from this paper can also be used for general purpose sparse interpolation. In that case the polynomial $R \in \mathbb{A}[x_1, ..., x_n]$ is given through an arbitrary blackbox function that can be evaluated at points in \mathbb{A} -algebras over some ring \mathbb{A} . This problem was studied in detail in [21]. In section 6, we investigated in particular how to replace expensive evaluations in cyclic \mathbb{A} -algebras of the form $\mathbb{A}[x]/(x^r-1)$ by cheaper evaluations at suitable *r*-th roots of unity in \mathbb{A} or a small extension of \mathbb{A} . The main new techniques from this paper were also anticipated in section 6.6.

The algorithms from this paper become competitive with the geometric sequence approach if the blackbox function is particularly cheap to evaluate. Typically, the cost *L* of one evaluation should be $L = O((\log t_R)^2)$ or $L = O((\log t_R)^3)$, depending on the specific variant of the geometric sequence approach that we use.

Technically speaking, it is interesting to note that the problem from this paper actually does *not* fit into this framework. Indeed, if *P* and *Q* are sparse polynomial that are represented in their standard expanded form, then the evaluation of R = PQ at a single point requires $L = O(s_P + s_Q + 1)$ operations in \mathbb{A} , and we typically have $L = \Theta(\sqrt{t_R})$. This is due to the fact that the standard blackbox model does not take into account possible speed-ups if we evaluate our function at many points in geometric progression or at *u* in a cyclic algebra $\mathbb{A}[u]/(u^r - 1)$.

Both in theory and for practical applications, it would be better to extend the blackbox model by allowing for polynomials *R* of the form

$$R = f(x_1, ..., x_n, U_1(x_1, ..., x_n), ..., U_m(x_1, ..., x_n)),$$

where $f \in \mathbb{A}[x_1, ..., x_n, y_1, ..., y_m]$ is a blackbox function and $U_1, ..., U_m \in \mathbb{A}[x_1, ..., x_n]$ are sparse polynomials in their usual expanded representation. Within this model, the techniques from this paper should become efficient for many other useful operations on sparse polynomials, such as the computation of gcds or determinants of matrices whose entries are large sparse polynomials.

5.4. Special types of support

The heuristic **HE** plays an important role in our complexity analysis. It is an interesting question whether it is satisfied for polynomials *R* whose support is highly regular and not random at all. A particularly important case is when *P*, *Q* and *R* are dense polynomials in *n* variables of total degrees d_P , d_Q and $d = d_R = d_P + d_Q$. Such polynomials are often considered to be sparse, due to the fact that *R* contains about *n*! times less terms than a fully dense polynomial of degree *d* in each variable.

If *R* is bivariate or trivariate and of very high degree, then it has been shown in [16] that *R* can be computed in approximately the same time as the product of two dense univariate polynomials which has the same number of terms as *R*. An algorithm for arbitrary dimensions *n* has been presented in [23], whose cost is approximately 3-2/n times larger than the cost of a univariate product of the same size. The problem has also been studied in [18, 19] and it is often used as a benchmark [12, 32].

What about the techniques from this paper? We first note that the exponents of *R* are known, so we can directly focus on the computation of the coefficients. In case that we need to do several product computations for the same *n* and *d*, we can also spend some time on computing a small τ and vectors $\lambda_1, \lambda_2, \lambda_3 \in \mathbb{Z}^n$ for which we know beforehand that we will win our game of mystery balls. For our simulations, we found it useful to

chose each λ_i among a dozen random vectors in a way that minimizes the sum of the squares of the number of balls in the boxes (this sum equals 22 for the first throw in Figure 1).

For various *n*, *d*, and τ , we played our game several times for different triples of vectors (λ_1 , λ_2 , λ_3). The critical value for τ for this specific type of support seems to be close to 1.14. In Table 5 below, we report several cases for which we managed to win for this value of τ . This *proves* that optimal polynomial multiplication algorithms for supports of this type are almost as efficient as dense univariate polynomial products of the same size.

п	2	2	2	3	3	3	4	4	5	7	10
d	100	250	1000	25	50	100	20	40	20	15	10
t	5151	31626	501501	3276	23426	176853	10626	135751	53130	170544	184756
τ	1.14	1.14	1.14	1.14	1.14	1.14	1.11	1.14	1.14	1.17	1.20

Table 5. The particular case when our sparse polynomials P, Q, R are dense polynomials in n variables of given total degrees d_P , d_Q and $d = d_R = d_P + d_Q$. The table shows values of τ for which it is possible to win the game of mystery balls for suitable evaluation points (we do not claim these values to be optimal).

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